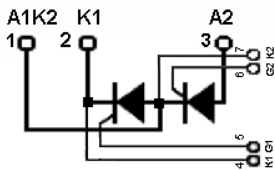


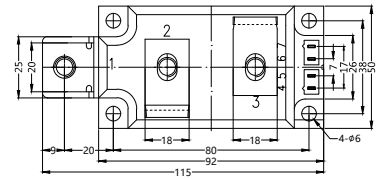
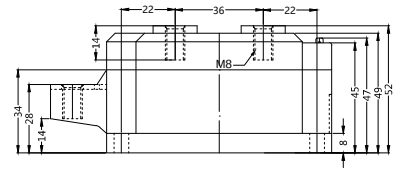
STT320GK26BT

Thyristor-Thyristor Modules



Type	V_{RSM} V_{DSM} V	V_{RRM} V_{DRM} V
STT320GK08BT	900	800
STT320GK12BT	1300	1200
STT320GK14BT	1500	1400
STT320GK16BT	1700	1600
STT320GK18BT	1900	1800
STT320GK20BT	2100	2000
STT320GK22BT	2300	2200
STT320GK24BT	2500	2400
STT320GK26BT	2700	2600

Dimensions in mm (1mm=0.0394")



Symbol	Test Conditions	Maximum Ratings	Unit
I_{TRMS} , I_{FRMS} I_{TAVM} , I_{FAVM}	$T_V = T_{VJM}$; 50Hz $T_C = 85^\circ\text{C}$; 180° sine	502 320	A
I_{TSM} , I_{FSM}	$T_V = 45^\circ\text{C}$ $V_R = 0$ $t = 10\text{ms}$ (50Hz), sine $t = 8.3\text{ms}$ (60Hz), sine	9100 10900	A
	$T_V = T_{VJM}$ $V_R = 0$ $t = 10\text{ms}$ (50Hz), sine $t = 8.3\text{ms}$ (60Hz), sine	8000 9600	
$\int i^2 dt$	$T_V = 45^\circ\text{C}$ $V_R = 0$ $t = 10\text{ms}$ (50Hz), sine $t = 8.3\text{ms}$ (60Hz), sine	414000 496000	A^2s
	$T_V = T_{VJM}$ $V_R = 0$ $t = 10\text{ms}$ (50Hz), sine $t = 8.3\text{ms}$ (60Hz), sine	320000 384000	
$(di/dt)_{cr}$	$T_V = T_{VJM}$ $f = 50\text{Hz}$, $t_p = 200\mu\text{s}$ $V_D = 2/3 V_{DRM}$ $I_G = 0.5\text{A}$ $di_G/dt = 0.5\text{A}/\mu\text{s}$	repetitive 150	A/ μs
	non repetitive	500	
$(dv/dt)_{cr}$	$T_V = T_{VJM}$; $V_{DR} = 2/3 V_{DRM}$ $R_{GK} = \infty$; method 1 (linear voltage rise)	1000	V/ μs
P_{GM}	$T_V = T_{VJM}$ $I_T = I_{TAVM}$ $t_p = 30\mu\text{s}$ $t_p = 500\mu\text{s}$	120 60	W
P_{GAV}		8	W
V_{RGM}		10	V
T_V T_{VJM} T_{stg}		-40...+125 125 -40...+125	$^\circ\text{C}$
V_{ISOL}	50/60Hz, RMS $I_{ISOL} \leq 1\text{mA}$ $t = 1\text{min}$ $t = 1\text{s}$	3000 3600	V~
M_d	Mounting torque (M6) Terminal connection torque (M8)	5 12	Nm
Weight	Typical	650	g

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Thyristor-Thyristor Modules

Symbol	Test Conditions	Characteristic Values		Unit
I_{RRM}, I_{DRM}	$T_{VJ}=T_{VJM}; V_R=V_{RRM}; V_D=V_{DRM}$	60		mA
V_{TM}	$I_{TM}=960A; T_{VJ}=25^{\circ}C$	$\leq 1800V$	2000-2600V	V
		1.85	2.20	
V_{TO}	For power-loss calculations only ($T_{VJ}=T_{VJM}$)	0.8		V
r_T		0.6		mΩ
V_{GT}	$V_D=6V;$ $T_{VJ}=25^{\circ}C$ $T_{VJ}=-40^{\circ}C$	2 2.6		V
I_{GT}	$V_D=6V;$ $T_{VJ}=25^{\circ}C$ $T_{VJ}=-40^{\circ}C$	200 250		mA
V_{GD}	$T_{VJ}=T_{VJM}; V_D=2/3V_{DRM}$	0.25		V
I_{GD}	$T_{VJ}=T_{VJM}; V_D=2/3V_{DRM}$	10		mA
I_L	$T_{VJ}=25^{\circ}C; t_p=30\mu s; V_D=6V$ $I_G=0.45A; di_G/dt=0.45A/\mu s$	1200		mA
I_H	$T_{VJ}=25^{\circ}C; V_D=6V; R_{GK}=\infty$	300		mA
t_{gd}	$T_{VJ}=25^{\circ}C; V_D=1/2V_{DRM}$ $I_G=0.5A; di_G/dt=0.5A/\mu s$	3		μs
t_q	$T_{VJ}=T_{VJM}; I_T=320A; t_p=200\mu s; -di/dt=10A/\mu s$ $V_R=100V; dv/dt=20V/\mu s; V_D=2/3V_{DRM}$ typ.	250		μs
Q_s	$T_{VJ}=T_{VJM}; I_T, I_F=320A; -di/dt=50A/\mu s$	650		μC
I_{RM}		235		A
R_{thJC}	per thyristor/diode; DC current per module	0.111 0.056		K/W
R_{thCH}	per thyristor/diode; DC current per module	0.04 0.02		K/W
d_s	Creeping distance on surface	12.7		mm
d_A	Creepage distance in air	9.6		mm
a	Maximum allowable acceleration	50		m/s ²

FEATURES

- * International standard package
- * Isolation voltage 3600 V~
- * Pressure Contacts Technology
- * UL File NO.E310749
- * RoHS Compliant

APPLICATIONS

- * Motor control
- * Power converter
- * Heat and temperature control for industrial furnaces and chemical processes
- * Lighting control
- * Contactless switches

ADVANTAGES

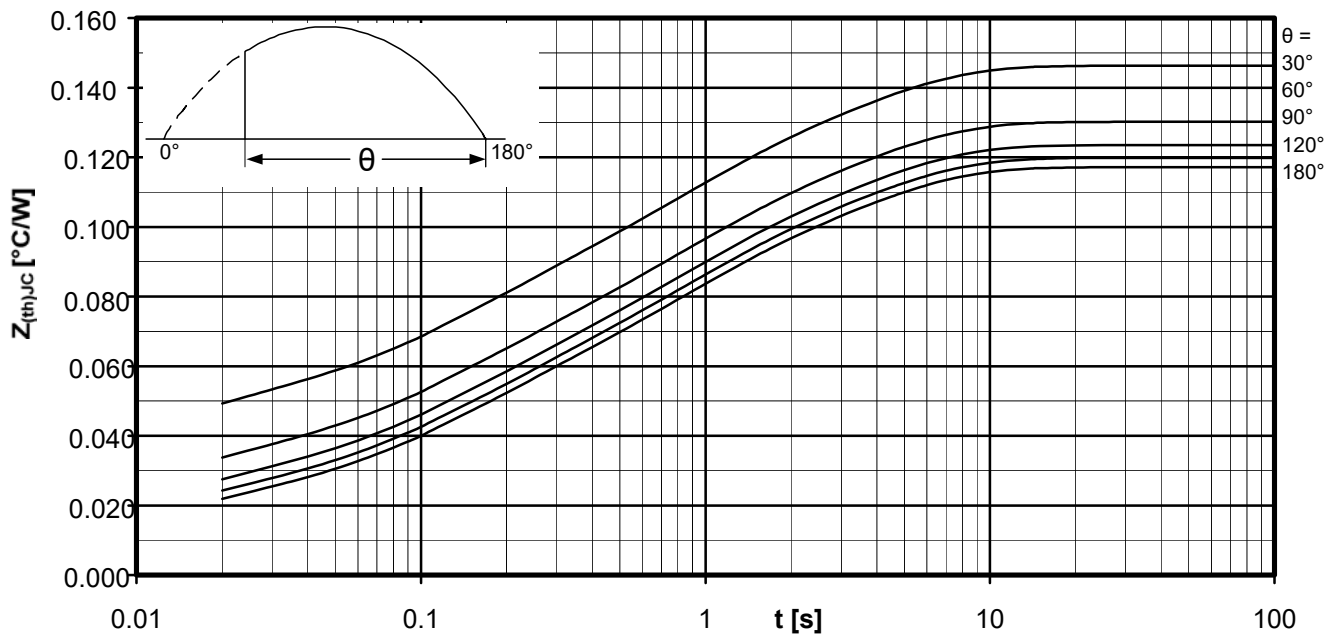
- * Space and weight savings
- * Simple mounting
- * Improved temperature and power cycling
- * Reduced protection circuits



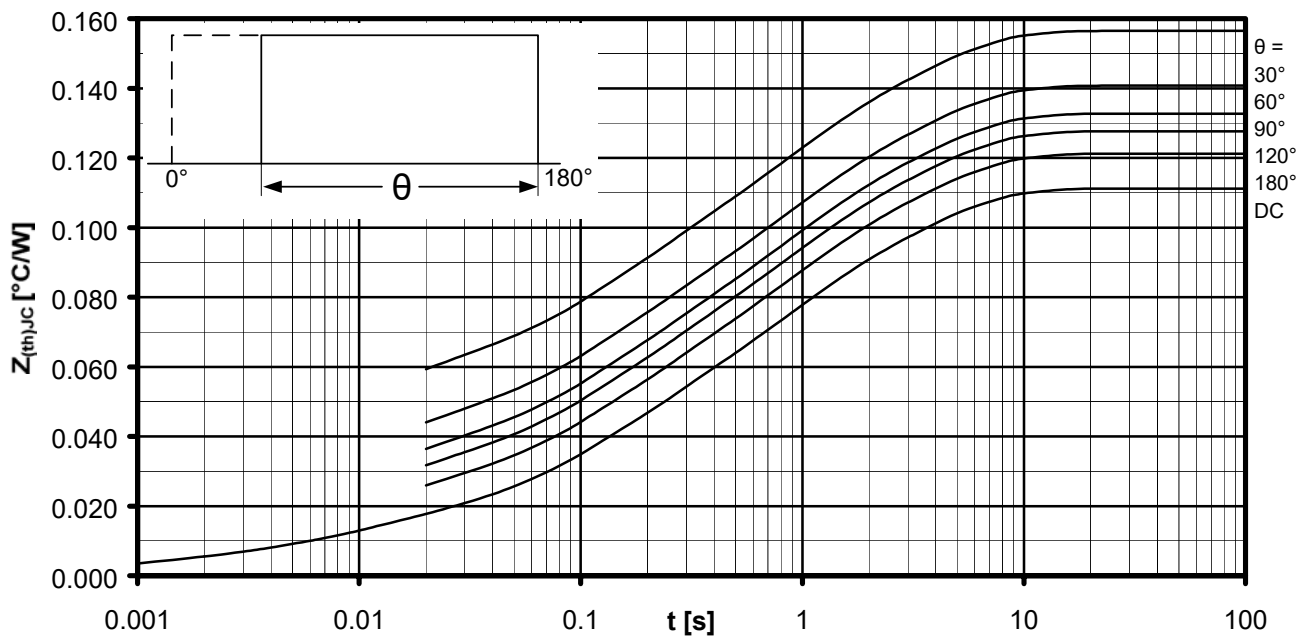
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Thyristor-Thyristor Modules



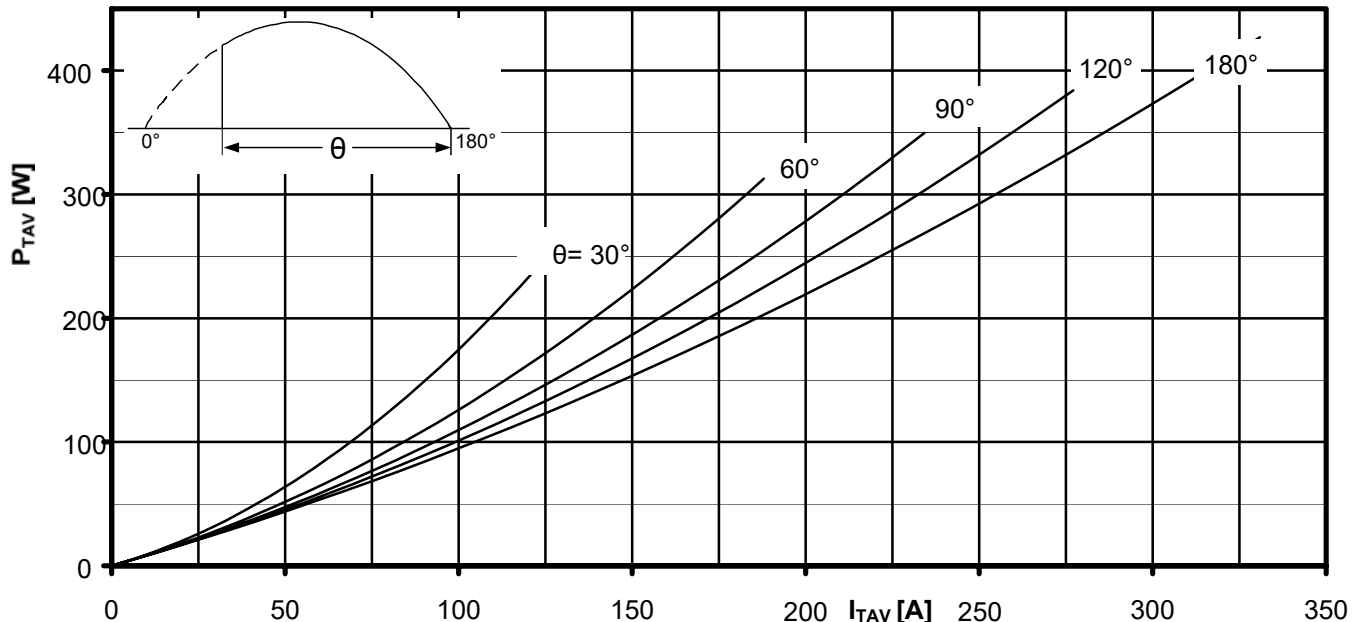
Transient thermal impedance per arm $Z_{thJC} = f(t)$
Sinusoidal current
Parameter: Current conduction angle θ



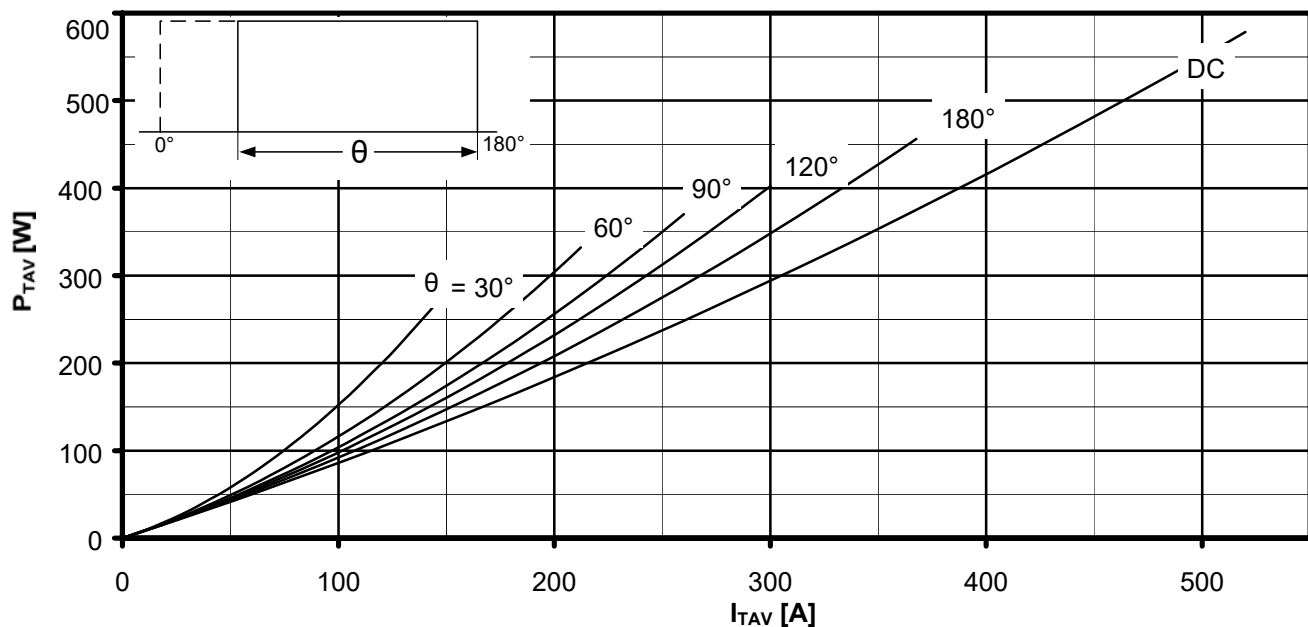
Transient thermal impedance per arm $Z_{thJC} = f(t)$
Rectangular current
Parameter: Current conduction angle θ

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Thyristor-Thyristor Modules



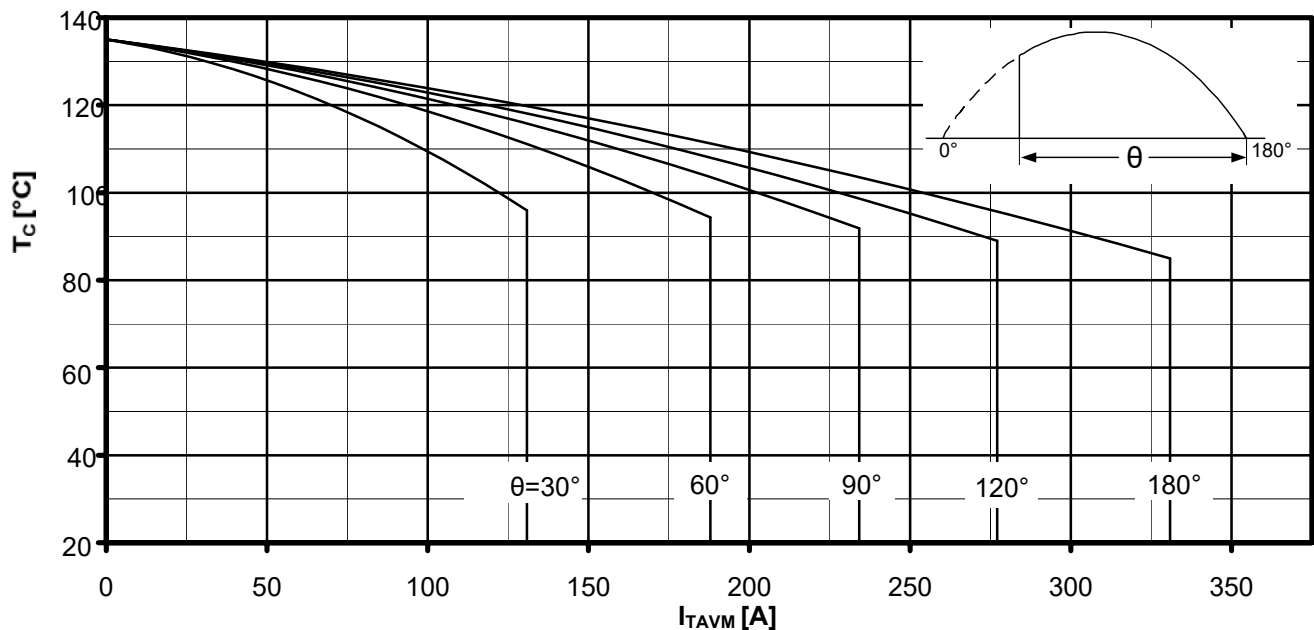
Calculation base P_{TAV} (switching losses should be considered separately)
Parameter: Current conduction angle θ



Calculation base P_{TAV} (switching losses should be considered separately)
Parameter: Current conduction angle θ

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Thyristor-Thyristor Modules

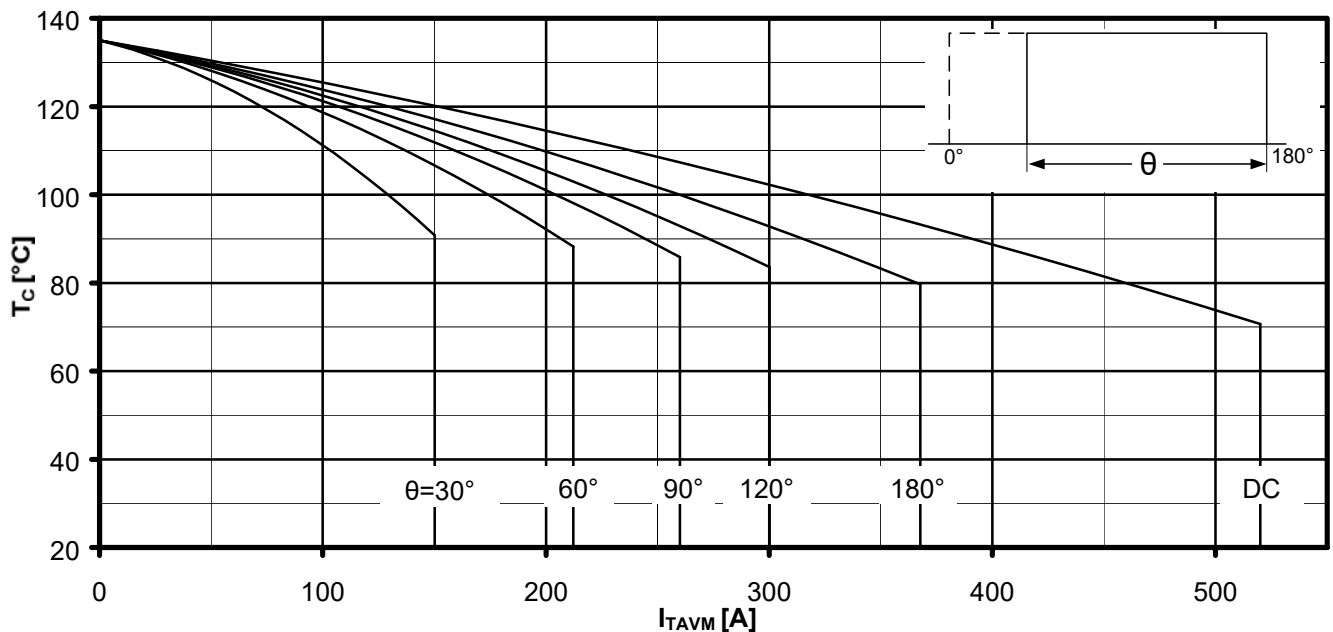


Maximum allowable case temperature $T_c = f(I_{TAVM})$

Sinusoidal current Current load per arm

Calculation base P_{TAV} (switching losses should be considered separately)

Parameter: Current conduction angle θ



Maximum allowable case temperature $T_c = f(I_{TAVM})$

Rectangular current Current load per arm

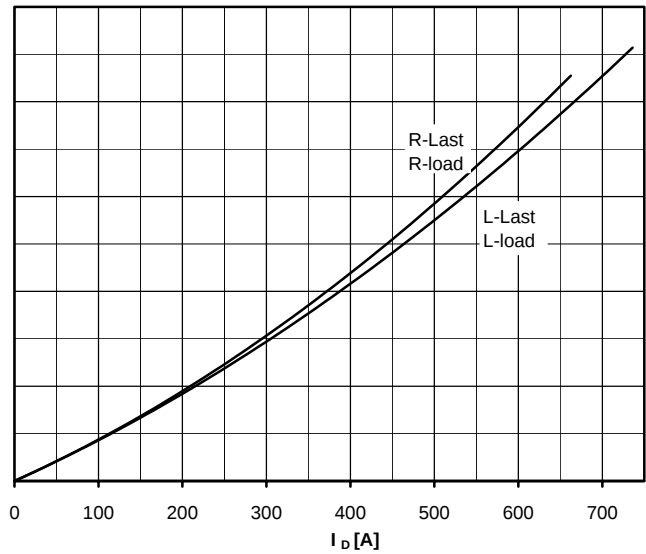
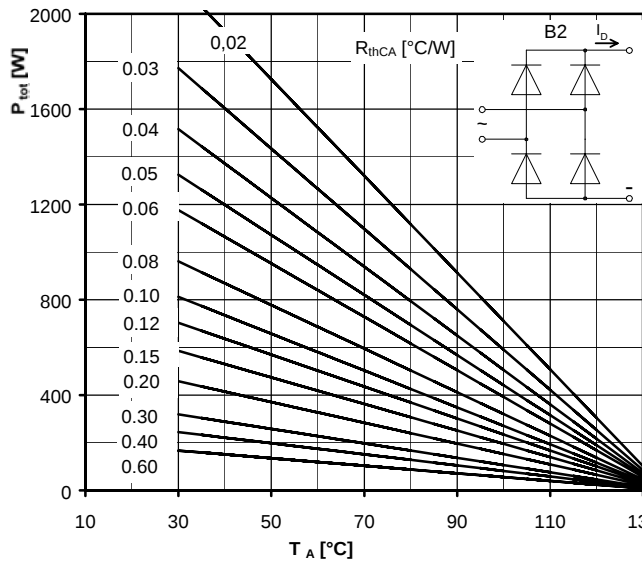
Calculation base P_{TAV} (switching losses should be considered separately)

Parameter: Current conduction angle θ

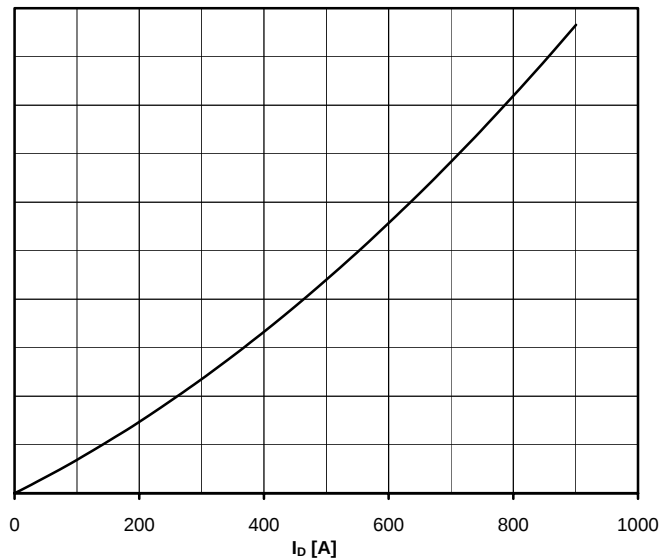
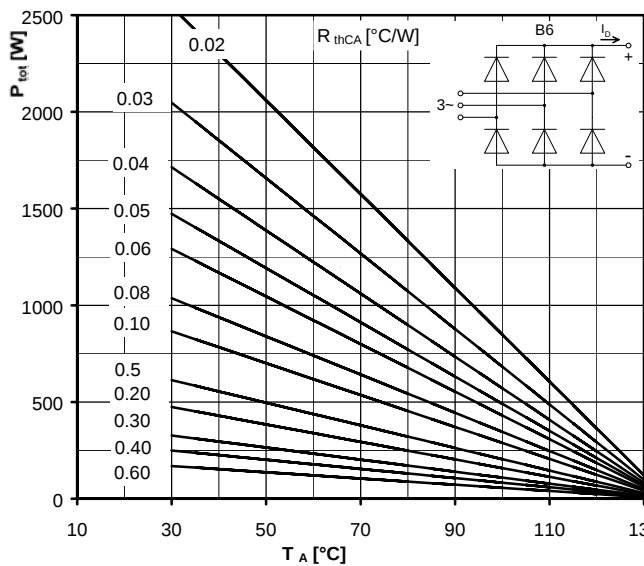
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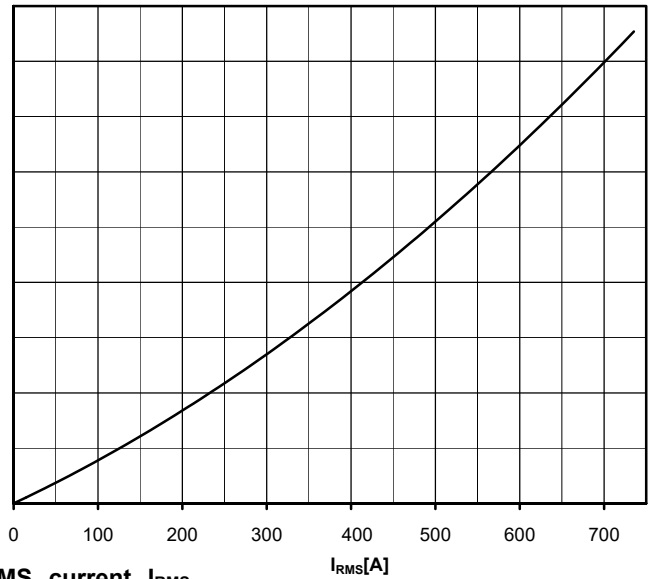
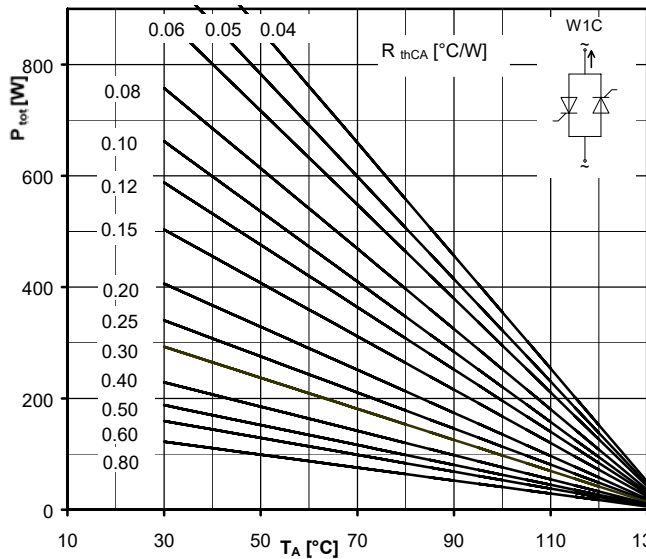
Maximum rated output current I_D
Two-pulse bridge circuit
Total power dissipation at circuit P_{tot}
Parameter:
Thermal resistance cases to ambient R_{thCA}



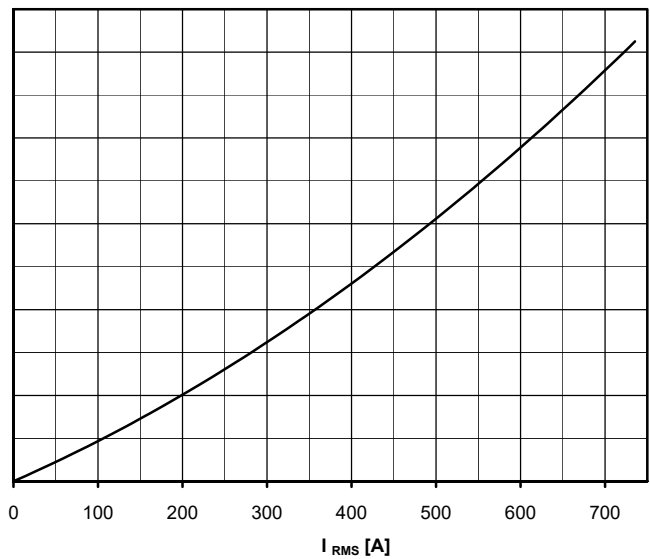
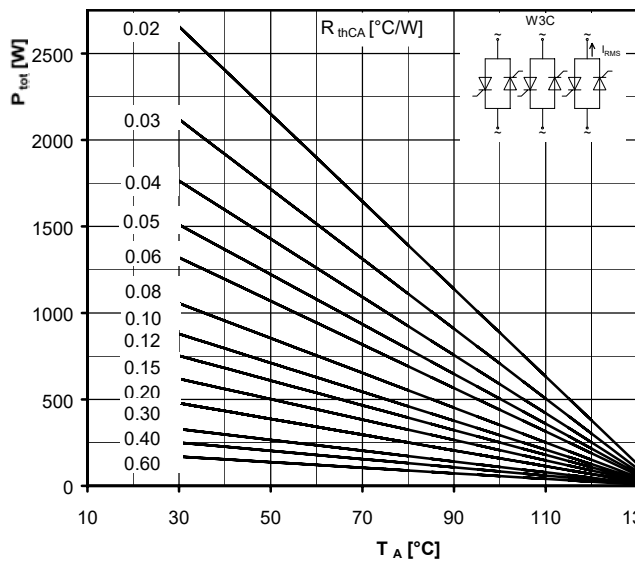
Maximum rated output current I_D
Six-pulse bridge circuit
Total power dissipation at circuit P_{tot}
Parameter:
Thermal resistance cases to ambient R_{thCA}

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Thyristor-Thyristor Modules



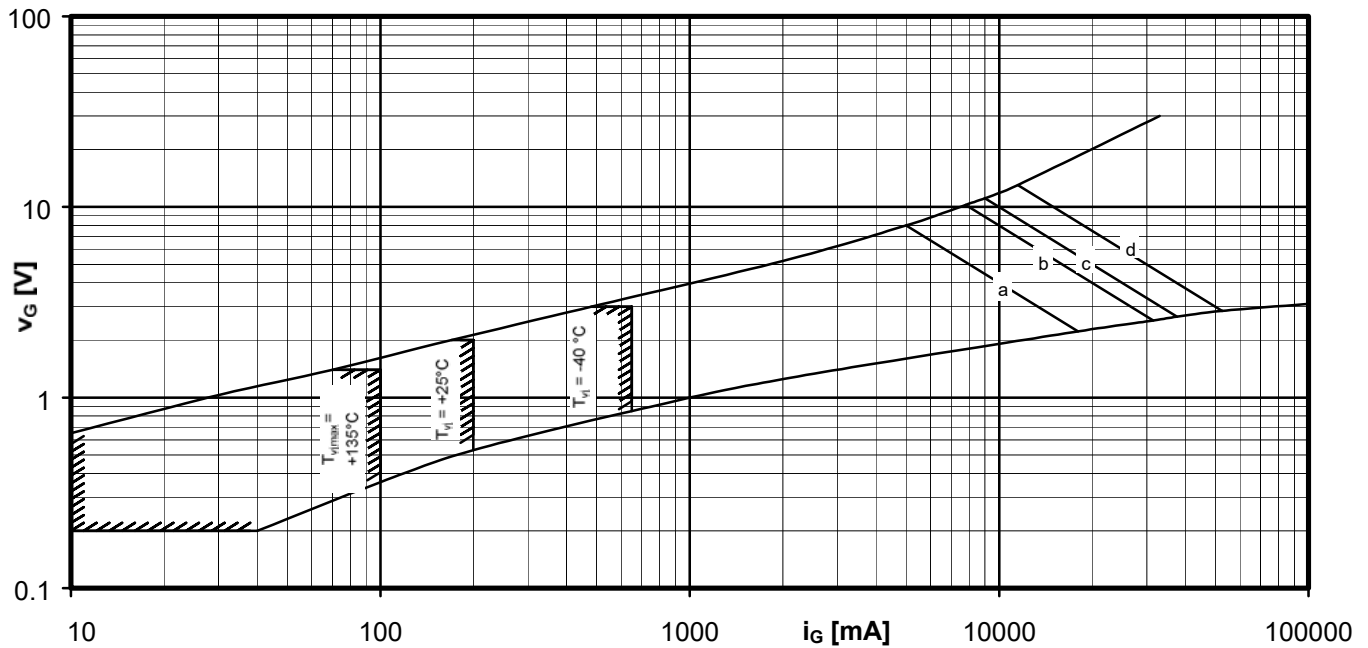
Maximum rated RMS current I_{RMS}
 Single-phase inverse parallel circuit
 Total power dissipation at circuit P_{tot}
 Parameter:
 Thermal resistance case to ambient R_{thCA}



Maximum rated RMS current I_{RMS}
 Three-phase inverse parallel circuit
 Total power dissipation at circuit P_{tot}
 Parameter:
 Thermal resistance cases to ambient R_{thCA}

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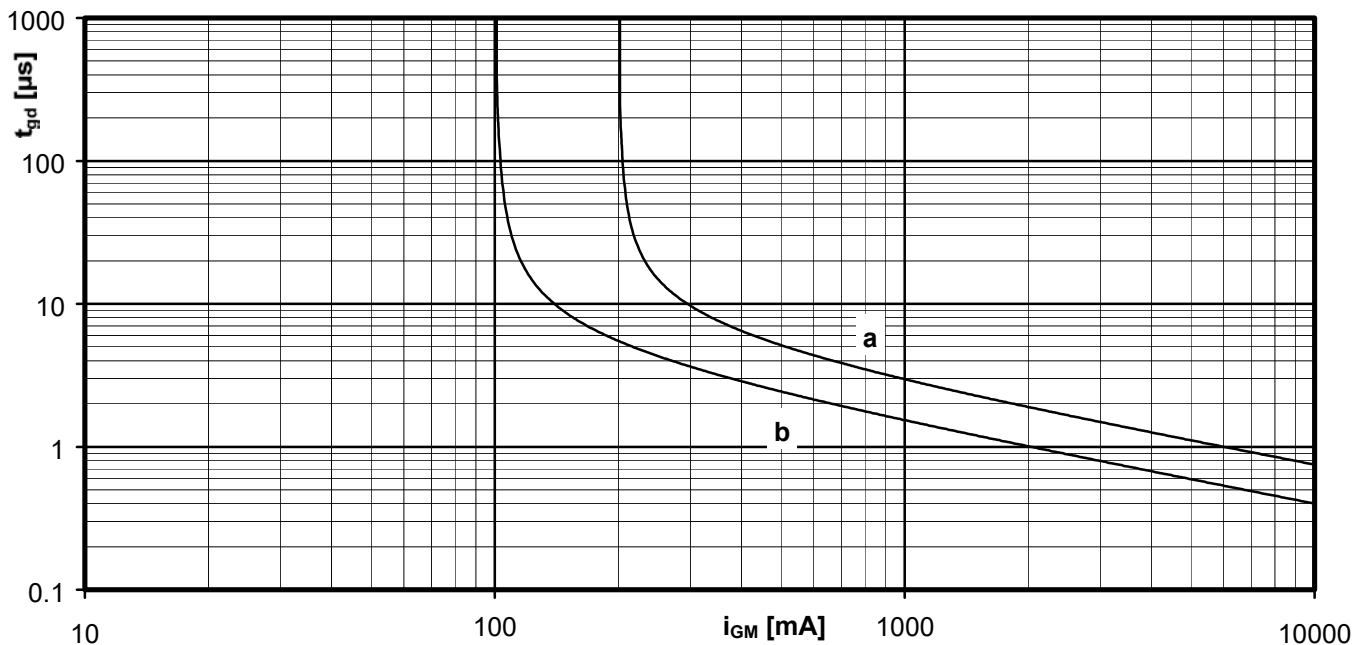
Thyristor-Thyristor Modules



Gate characteristic $v_G = f(i_G)$ with triggering area for $V_D = 6\text{ V}$

Maximum rated peak gate power dissipation $P_{GM} = f(t_g)$:

a - 40 W/10ms b - 80 W/1ms c - 100 W/0,5ms d - 150W/0,1ms



Gate controlled delay time $t_{gd} = f(i_G)$ $T_{vj} = 25^\circ\text{C}$,

$di_G/dt = i_{GM}/1\mu\text{s}$

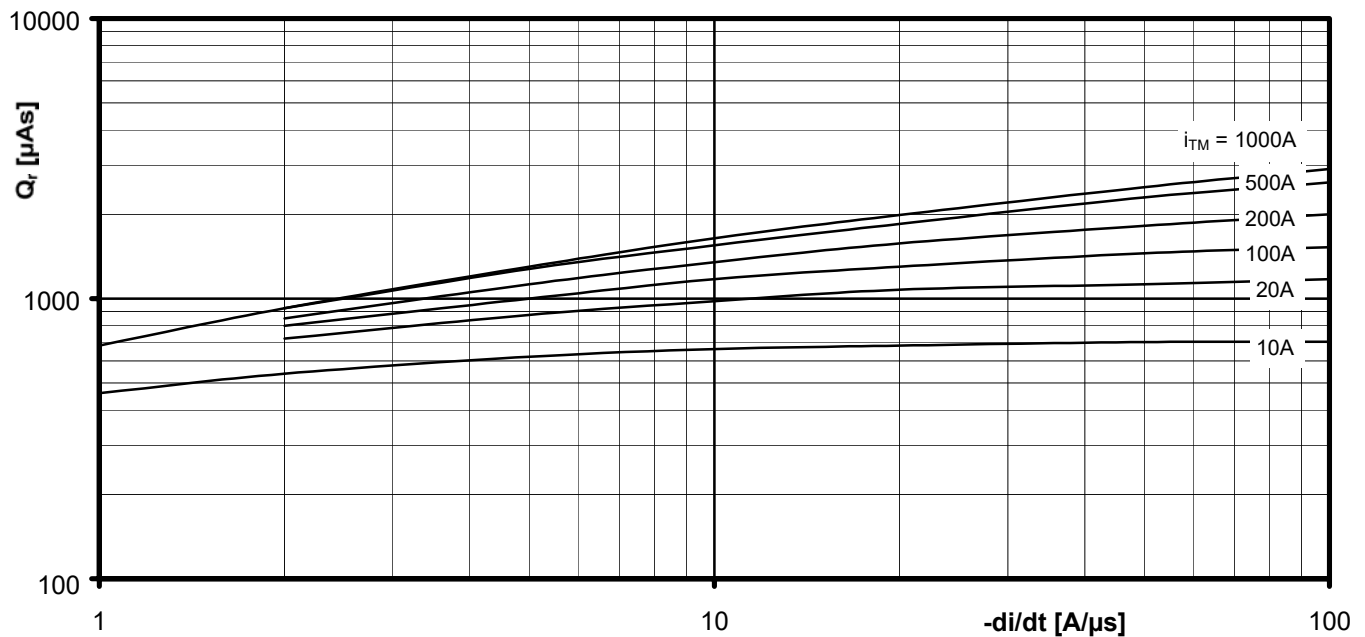
a - Limiting characteristic

b - Typical characteristic

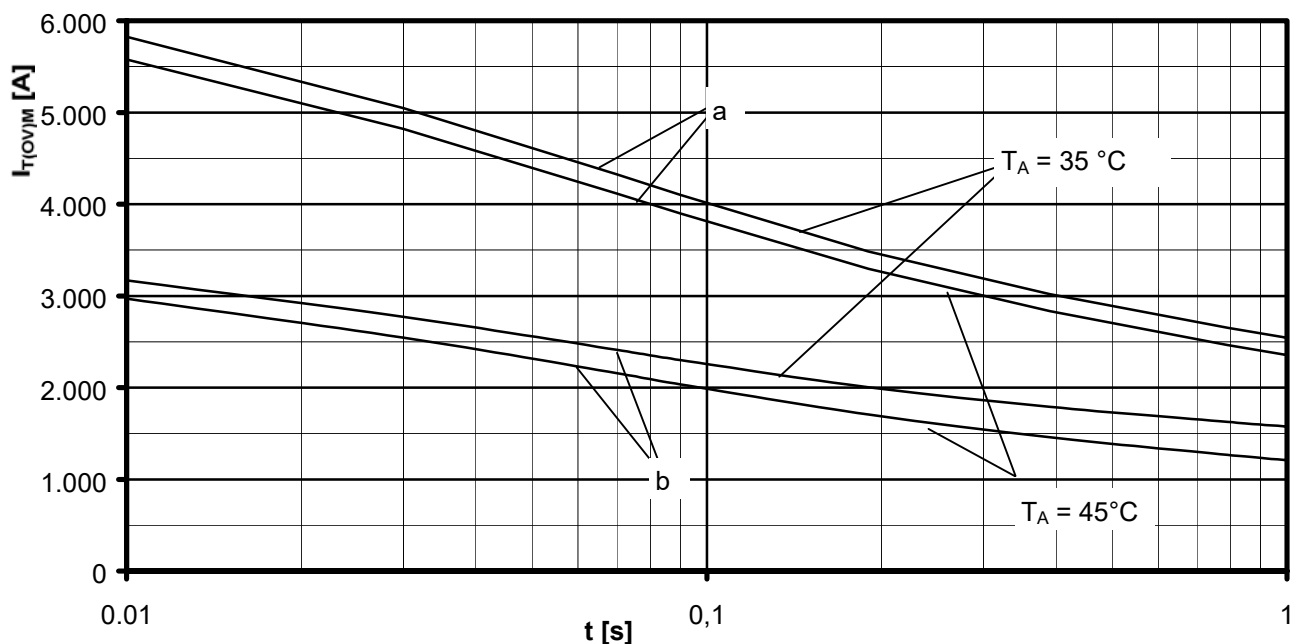
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Recovered charge $Q_r = f(-di/dt)$
 $T_{vj} = T_{vjmax}$, $V_R \leq 0,5 V_{RRM}$, $V_{RM} = 0,8 V_{RRM}$
 Parameter: On-state current i_{TM}

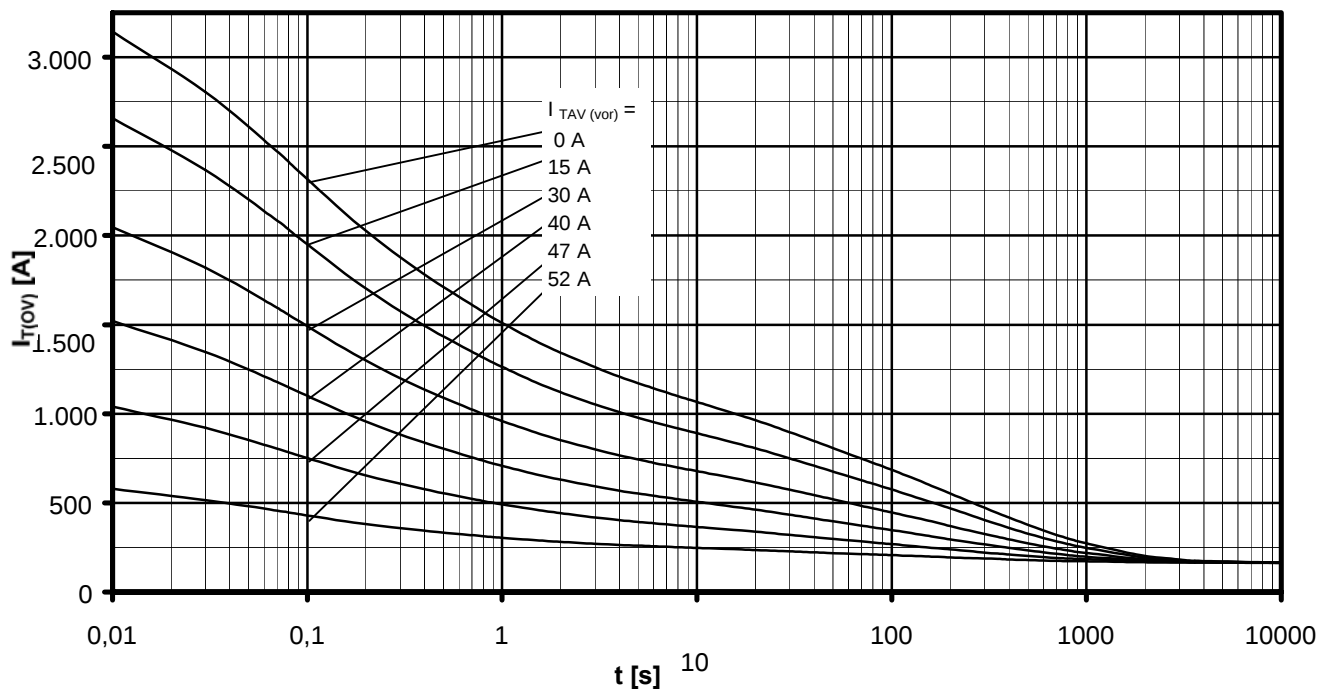


Maximum overload on-state current $I_{T(OV)M} = f(t)$, $v_{RM} = 0,8 V_{RRM}$

a: No-load conditions
 b: after load with I_{TAVM}
 $T_A = 35^\circ C$, Forced air cooling
 $T_A = 45^\circ C$, Natural air cooling

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Thyristor-Thyristor Modules

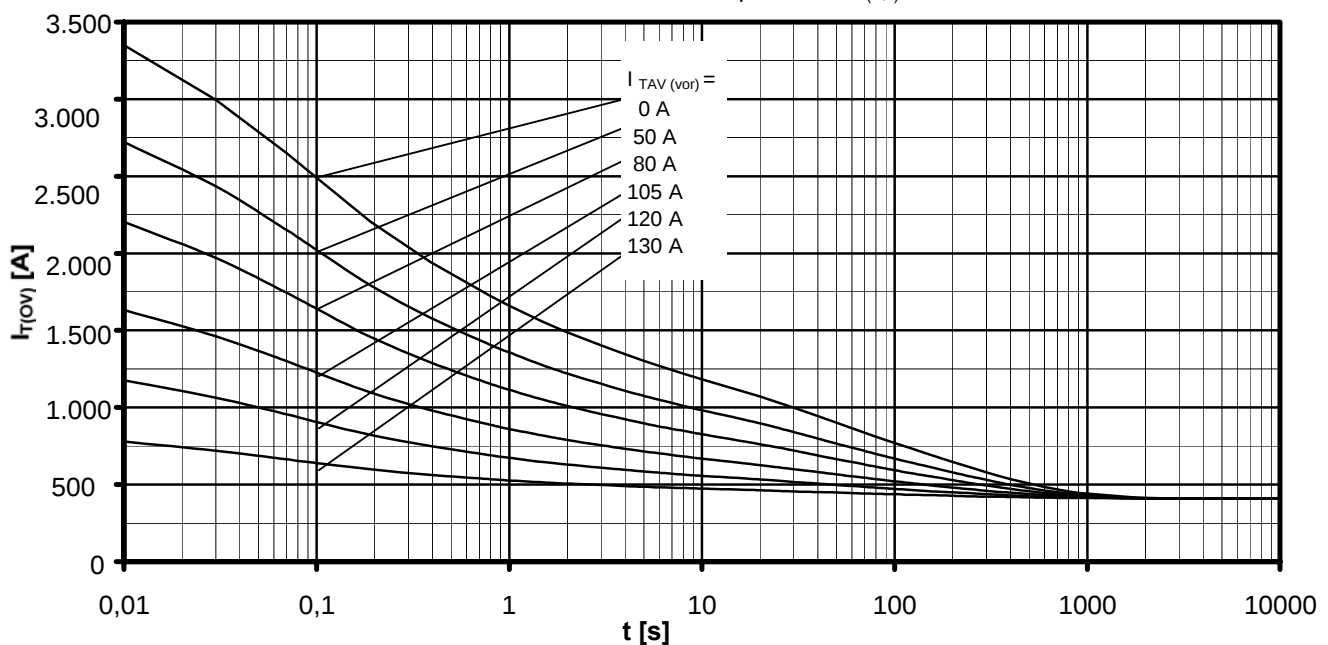


Overload on-state current $I_{T(ov)}$

Six-pulse bridge circuit, 120° rectangular

Heatsink type KM17 (45W) Natural cooling at $T_A = 45^\circ\text{C}$

Parameter: Pre-load current per arm $I_{TAV(vor)}$



Overload on-state current $I_{T(ov)}$

Six-pulse bridge circuit, 120° rectangular

Heatsink type KM17(45W) Forced cooling at $T_A = 35^\circ\text{C}$

Parameter: Pre-load current per arm $I_{TAV(vor)}$

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